## Sambuddha Sarkar



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Machine Learning, Statistical Techniques in Robotics, Computer Vision, Camera Calibration, 3D Reconstruction, Robotics & Manipulation, Systems Engineering Medical & Assistive Technologies, Wearable Technology, 3D Modelling & Simulation, CAD & Product Design.

EDUCATION August'16 - December'17	Carnegie Master o Expected GPA: 3.62 VIT Unive B.Tech, E CGPA: 9. Rank 13/2	e Mellon University, Pittsburgh, USA f Sc. In Robotic Systems Development (MRSD)RELEVANT COURSE-WORK1 : December 2017 2/4.00- Applied Machine Learning - Statistical Techniques in Robotics - Computer Vision - Geometric Based Methods in CV - Robot Autonomy - Biomechanics & Motor Control - Manipulation, Mobility & Control - Systems Engineering2/4.00- Applied Machine Learning - Statistical Techniques in Robotics - Computer Vision - Geometric Based Methods in CV - Robot Autonomy - Biomechanics & Motor Control - Manipulation, Mobility & Control - Systems Engineering
SKILLS Machine Learning, Computer Vision, Robotics & Manipulation, Embedded Systems, Analog Circuit Design, PCB design, CAD, Graphic Designing, Fabrication	<ul> <li>Softv Octav</li> <li>Prog</li> <li>CAD:</li> </ul>	<b>vare/Utility/Framework/Simulation</b> : Arduino IDE, Atmel Studio, Proteus(ISIS/ARES), Keil μVision IDE, MATLAB, /e, NI LabVIEW, ABB Robot Studio,ROS, AEROTECH:A3200 Motion Composer, WEKA, LightSide. <b>ramming/Scripting:</b> Python, MATLAB, Octave, C, C++, HTML5. Blender3D, SolidWorks, EagleCAD, Fritzing.
HONORS Riga Technical University, L' March'16 - July'16	Erasmus V An EU(Eur Robots.	+ KA1 Mobility Program: Faculty of Electronics & Telecommunications ropean Commission) sponsored student exchange program. Completed Bachelor's Thesis on Bio-inspired Walking in
WORK HIGHLIGHTS		
<b>Proto Innovations, US</b> May'17 — Dec'17	Summer Internship & Independent Study	Machine Learning based Slip Estimation on NASA Planetary Rover: Applied Machine Learning Engineer & Co-Systems Engineer Real-time Slip Estimation on NASA Planetary rovers using various Supervised Machine Learning Models deployed using ROS. Keywords: Python, ROS, Scikit-Learn, WEKA, LightSide.
Oculus Research Pittsburgh, US August'16 — May'17	MRSD Capstone	Multi-Sensor Calibration (Camera Calibration): Automation & Control Engineer, Simulation Engineer, Calibration Engineer Autonomous and high-speed online calibration of multiple cameras for 3D reconstruction. Keywords: AEROTECH, ABB, Blender 3D, Python, MATLAB, A3200 Controllers.
<b>VIT University, IN</b> August'15 — November'15	Course Project	DANI – Robotic Hand: Electrical and Mechanical Engineer Dextrous, Anthropomorphic and Intelligent (DANI) robotic hand with adaptive grasping.
<b>Dept. of Science and Technology, IN</b> February'14 — August'15	Research Project	Fuel Level and Quality sensor: Electrical Engineer, Sensing Engineer & Independent Researcher. Capacitance based fuel level sensor with anti-slosh and error reducing algorithm.
<b>Johnson Controls, IN</b> Məy'14 — July'14	Summer Internship	Building Management Systems: Automation Engineer, Electrical Engineer Worked on networked controllers for HVAC/R systems. Familiarization with proprietary reporting tool EDART.
<b>BAJA SAE INDIA</b> January'14 — April'14	Collegiate Team	Data Acquisition (DAQ): Circuit & Sensor Designer, Electrical Engineer Model, design, test and implement a on-board DAO system to map gear ratios of the VIT University's ATV's CVT in real time.

## **RELEVANT SIDE/COURSE PROJECTS**

Robotic Sonic Drilling using Multi Armed Bandits as Drill Agents(Simulation) – OCR using Deep Networks – 3D Face Tracking & Land Mark Detection – Optical Flow (Inverse Lucas Kanade) – Image feature detection(BRIEF-RANSAC) – Extended Kalman Filter-SLAM(2D Robot) – Scene Classification(Spatial Pyramid Matching) – Musical Instrument Recognition(LVQ – Clustering – ANN) Bazooka(Spud Cannon) – Stun Gun – Grid Follower Bot – Maze Solving Robot – SAE Aero Design East

## HACKATHONS

- Make-a-thon 2014, Team Wi-Pi; Electrical Engineer & Product Designer
- Wi-Pi, a portable and efficient RasPi based voice assistant with special modules that can help blind people get access to news and other media.
- Prototype 2014, Team Pineapple; Project Leader, Electrical Engineer
- Nixie Proto, an ATmega32 based portable array of sensors that can test for water quality, including bacterial contamination by utilising Impedance Spectroscopy and a Neural Network based classifier.
- Jugaaad-a-thon 2015, Team Aceso; Project Leader, Electrical Engineer Early detection of Maternal Sepsis: Designed and built a smart belt which could monitor all the vital parameters of a pregnant mother and if the threshold was violated then an alarm would be raised. (ECG monitoring : Heart rate and B.P., Body Temperature)

## RESPONSIBILITIES

- Oculus Research Pittsburgh; Project Manager(Fall 2016): MRSD Capstone project.
- IEEE Electron Devices Society; Graphic Designer, Electronics Engineer : VIT University Student Chapter.
- Flying INC.; Technical Division, Electrical Dept. : SAE Aero Design East : Collegiate Design Team building fixed wing aircrafts.
- Team Kshatriya; Technical Division, Electrical Dept. & Graphic Designer : BAJA SAE INDIA : Collegiate Design Team building All Terrain Vehicles (ATV).